# Week 10 Background Modeling

Ref: Stauffer, C. & Grimson, W. E. L. (1999). Adaptive Background Mixture Models for Real-Time Tracking.. CVPR (p./pp. 2246-2252), : IEEE Computer Society. ISBN: 0-7695-0149-4



## Motion

- 1. Motion of blocks Motion Vectors
- 2. Motion of Objects Object Tracking
- 3. Motion Regions Background Modeling

# **Object:** regions of the image that are semantically important



#### Moving Object Detection in Fixed Camera Videos



# Idea: Model the Background!



# Task: differentiate the moving objects from the background!



#### The pixel is Foreground or Background?

### Idea: -single value modeling of background

![](_page_8_Picture_1.jpeg)

# Challenge: Acquisition noise

![](_page_9_Picture_1.jpeg)

#### Idea: Single Gaussian Model

- If  $|X_t \mu| < 2.5 * \sigma$ - background,
- Else

   foreground

![](_page_10_Figure_4.jpeg)

# Challenge: Illumination Variation

![](_page_11_Picture_1.jpeg)

# Idea: adapt the parameters!

![](_page_12_Figure_1.jpeg)

$$\mu_t = (1 - \rho)\mu_{t-1} + \rho X_t$$
$$\sigma_t^2 = (1 - \rho)\sigma_{t-1}^2 + \rho (X_t - \mu_t)^T (X_t - \mu_t)$$

where

$$\rho = \alpha \eta(X_t | \mu_k, \sigma_k)$$

![](_page_13_Figure_3.jpeg)

# Challenge: Clutter

![](_page_14_Picture_1.jpeg)

# Idea: Use multiple Gaussians

![](_page_15_Picture_1.jpeg)

![](_page_15_Figure_2.jpeg)

# Challenge: new objects in the scene!

![](_page_16_Picture_1.jpeg)

### Idea: more Gaussians, store foreground as well!

![](_page_17_Picture_1.jpeg)

![](_page_17_Figure_2.jpeg)

#### Persistence

- Modeled as prior weight w
- If a new pixel does not match to any exiting Gaussians, least persistent Gaussian is replaced with a new Gaussian with:

$$\mu_t = P_t$$

And standard variation

 $\sigma_t$  = a large value

### **Background Selection**

- A background Gaussian will have
  - More persistence high w
  - Less variation low  $\sigma_t$
  - Sort Gaussians wrt  $w/\sigma_t$

$$\arg\min_{k}\left(\sum_{i=1}^{k} w_{i} > T\right)$$

#### Adaptive Background Model

#### **Outline of Object Detection**

![](_page_21_Picture_1.jpeg)

CLEANED UP

![](_page_21_Picture_3.jpeg)

# Connecting the Dots

- Dilation/Erosion
- Contour drawing
- Bounding boxes

# **Revisiting Challenges**

- Acquisition noise
- Illumination variation
- Clutter
- New object introduced into background
- Object may not move continuously

![](_page_23_Picture_6.jpeg)

#### All models are wrong but some are useful. -George E. P. Box